

SELF-TIMED CIRCUITRY RETROSPECTIVE

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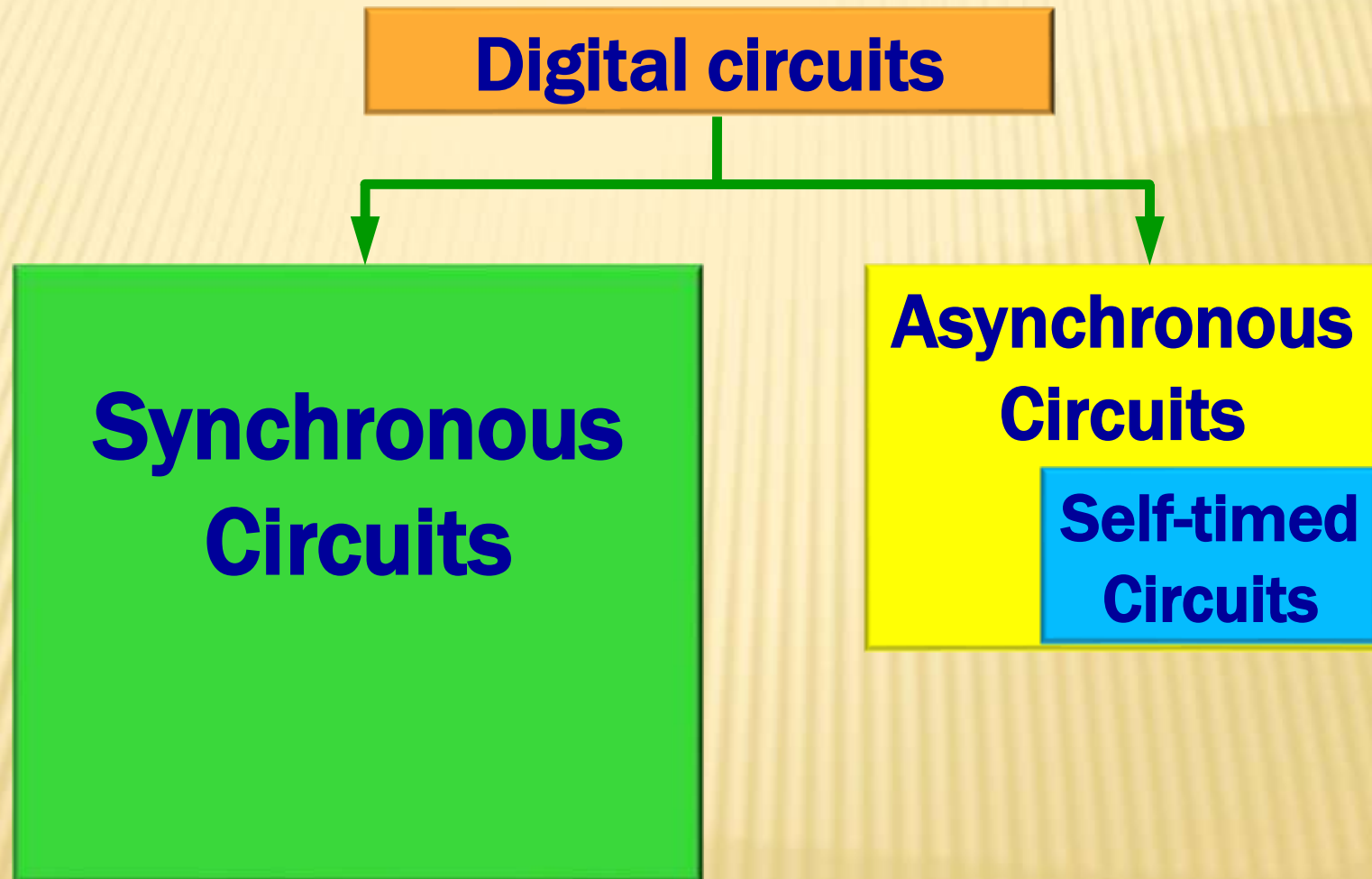


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- ▣ **Self-timed circuit – what is it?**
- ▣ **Self-timed circuit features**
- ▣ **Self-timed Micro Core**
- ▣ **Self-timed Coprocessor**
- ▣ **Self-timed circuit optimization**
- ▣ **Conclusions**

CIRCUITS DESIGN METHODOLOGIES



SELF-TIMED CIRCUIT FEATURES

▣ Advantages:

- ❖ Stable operation under any operating conditions
- ❖ Wide range of workability
- ❖ Natural full self-checking concerning constant faults
- ❖ Lack of overhead hardware and energy costs associated with global clock tree

▣ Drawbacks:

- ❖ Hardware redundancy
- ❖ Increased number of signals

SELF-TIMED CIRCUIT TYPES

Quasi-Speed-Independent (QSI) circuits

- ❖ Do not depend on cell's delays
- ❖ Critical path indication only

Speed-Independent (SI) circuits

- ❖ Do not depend on cell's delays
- ❖ Full indication
- ❖ Purely self-timed in isochronous zone

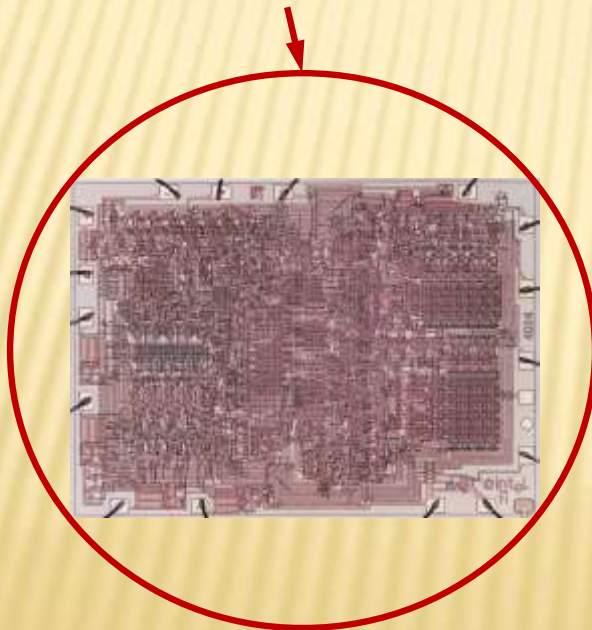
Delay-Insensitive (DI) circuits

- ❖ Do not depend on delays both in cells and wires
- ❖ Full indication

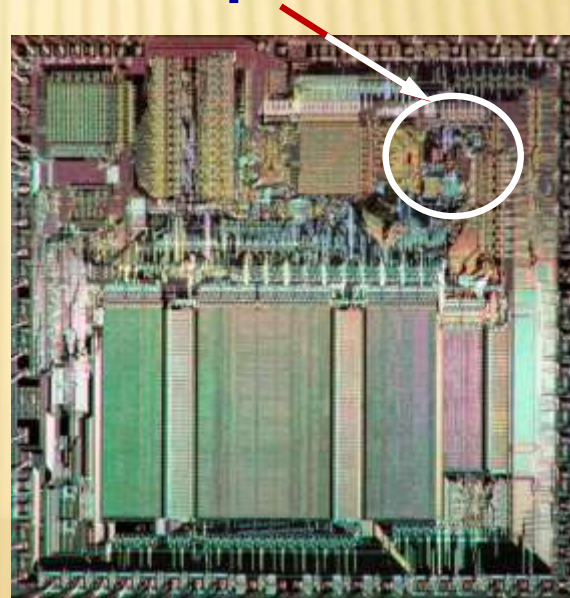
ISOCHRONOUS ZONE

Delay in any wire is less than the least delay of any library cell

In 1- μm and higher CMOS process



In deep submicron CMOS process



SPEED-INDEPENDENT CIRCUIT BASE PRINCIPLES

- ❖ **Two-phase operation mode: working phase and spacer**
- ❖ **The use of dual-rail, biphasic and unary information signals**
- ❖ **Acknowledging the switching of all circuit cells by an additional indication subcircuit**
- ❖ **Handshake between subsequent functional blocks in the information processing path**
- ❖ **Unlimited circuitry basis**

DELAY-INSENSITIVE CIRCUIT BASE PRINCIPLES

NULL Convention Logic (NCL) is a typical representative of the DI circuits

- ❖ **Two-phase operation mode: working phase and spacer**
- ❖ **The use of dual-rail only information signals**
- ❖ **Each cell indicates all own inputs**
- ❖ **Limited multi-threshold cell library (29 cells)**

SI AND NCL CIRCUITS COMPARISON

	SI circuits	NCL circuits
Advantages	<ul style="list-style-type: none">✓ Less complexity (up to 2 times for combinational circuits and up to 4 times for sequential ones)✓ Unlimited cell basis✓ Analysis software	<ul style="list-style-type: none">✓ Simple indication (only circuit outputs should be indicated)✓ Easier design automation (BALSA, UNCLE)
Drawbacks	<ul style="list-style-type: none">▪ Additional indication subcircuit controlling all circuit cells▪ Hard formalization for design automation	<ul style="list-style-type: none">▪ Large complexity both of combinational and sequential circuits▪ Less performance▪ Larger power consumption

SOFTWARE FOR SI CIRCUIT DESIGN DEVELOPED IN FRC “CSC”

Self-timing properties analysis:

- ❖ **Library cell level analysis (BTRAN, ASIAN)**
- ❖ **Functional block level analysis (ASPECT)**
- ❖ **VLSI level hierarchical analysis (LIMAN)**

SI circuit synthesis:

- ❖ **Custom and gate arrays base**
- ❖ **Industrial standard cell libraries extended by self-timed combinational and sequential cells**

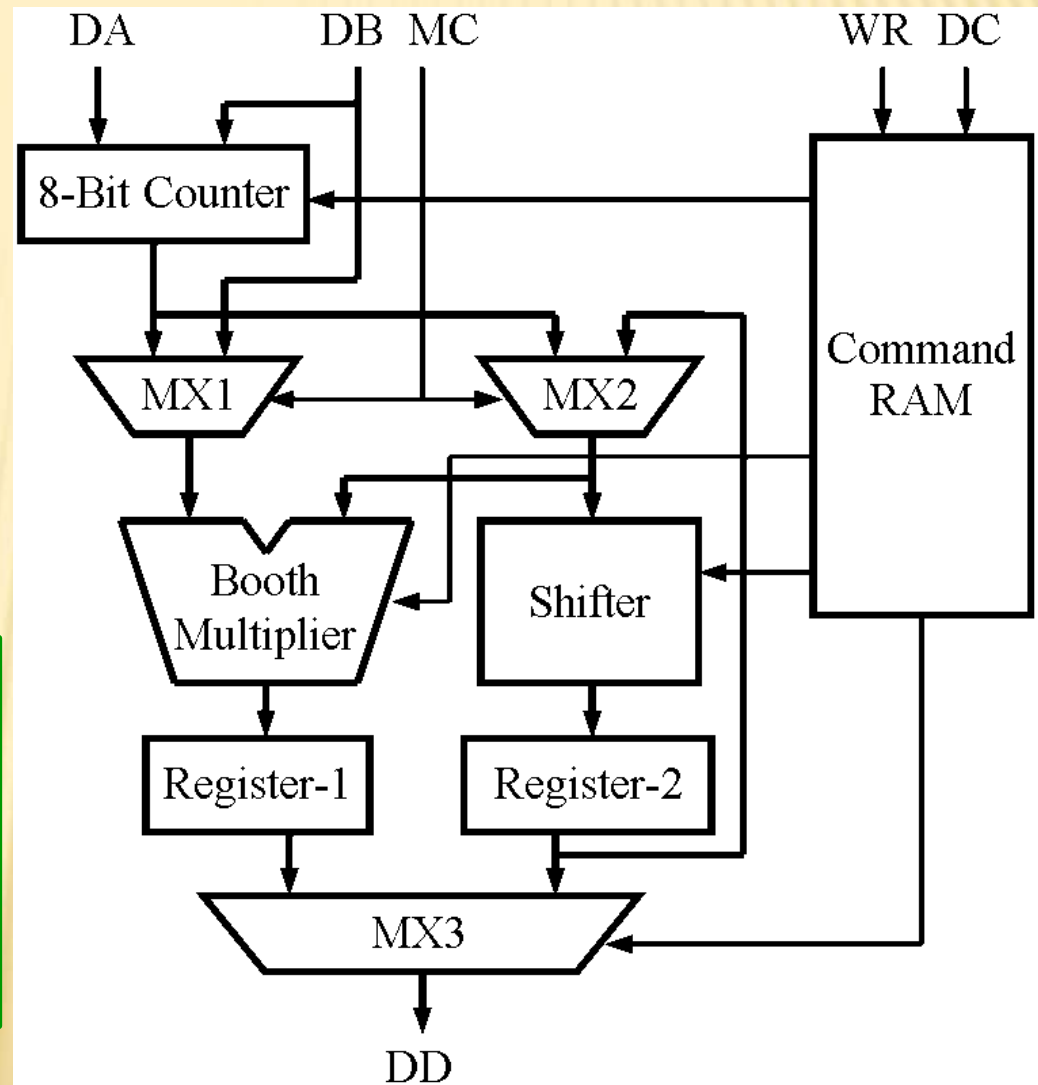
SI CIRCUIT EXAMPLES: MICRO CORE

Instruction Set:

MUL – multiply 4×4
ROT – cyclic shift
JUMP – unconditional jump
NOP – no operation

CMOS Process

- 1.6 μm
- 1 metal, 1 polysilicon
- Gate Array



SI CIRCUIT EXAMPLES: MICRO CORE

Operation cycle duration for command sets

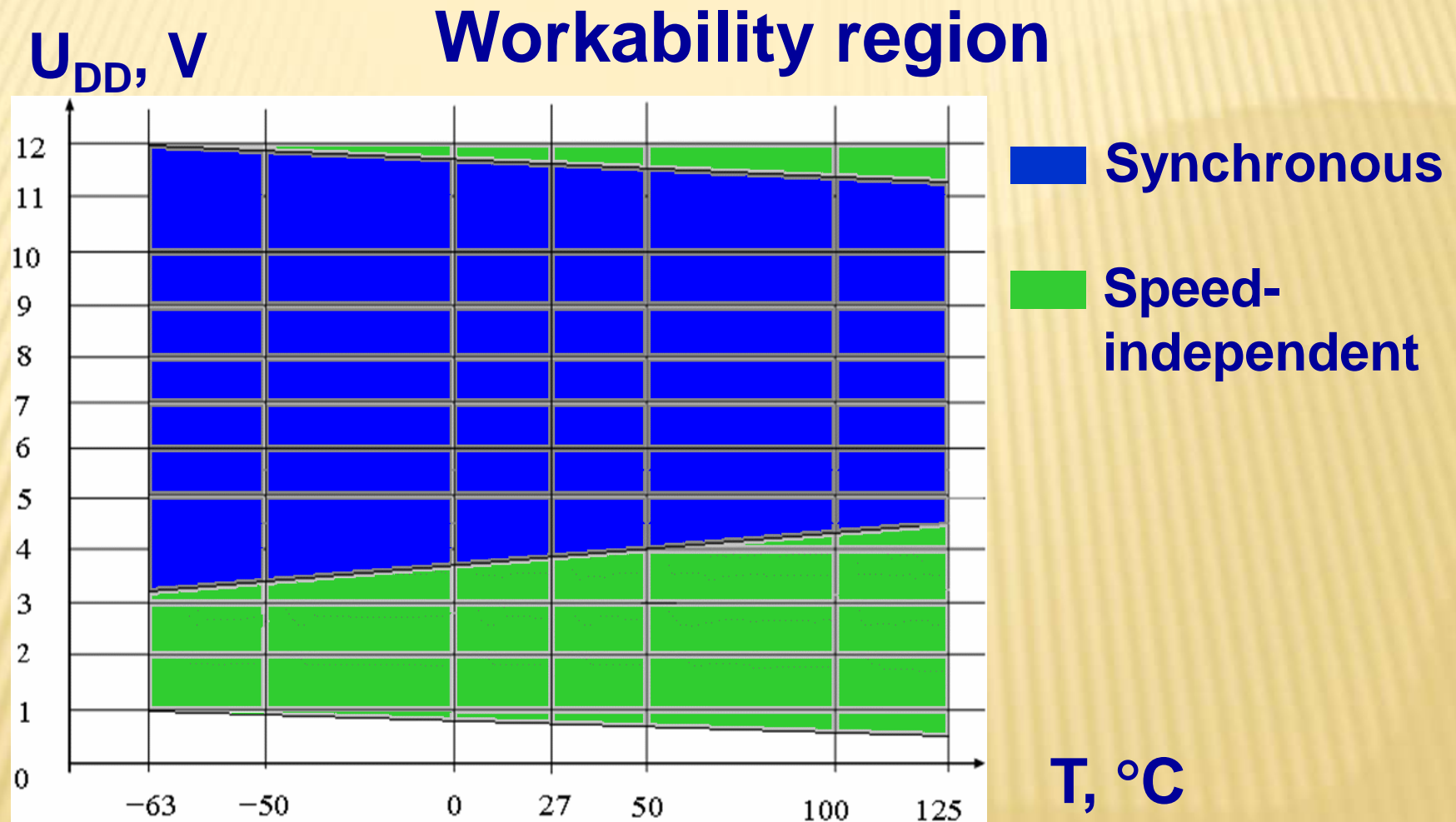
	Operation set	Synch-ronous, ns	Speed-independent, ns		
		typical	worst	typical	best
1	Cyclic MUL	250	166	144	118
2	Cyclic ROT	250	121	102	86
3	Cyclic NOP	250	111	93	75
4	Cyclic JUMP	500	90	78	66
5	MUL + JUMP + NOP + ROT	1248	516	440	364

SI CIRCUIT EXAMPLES: MICRO CORE

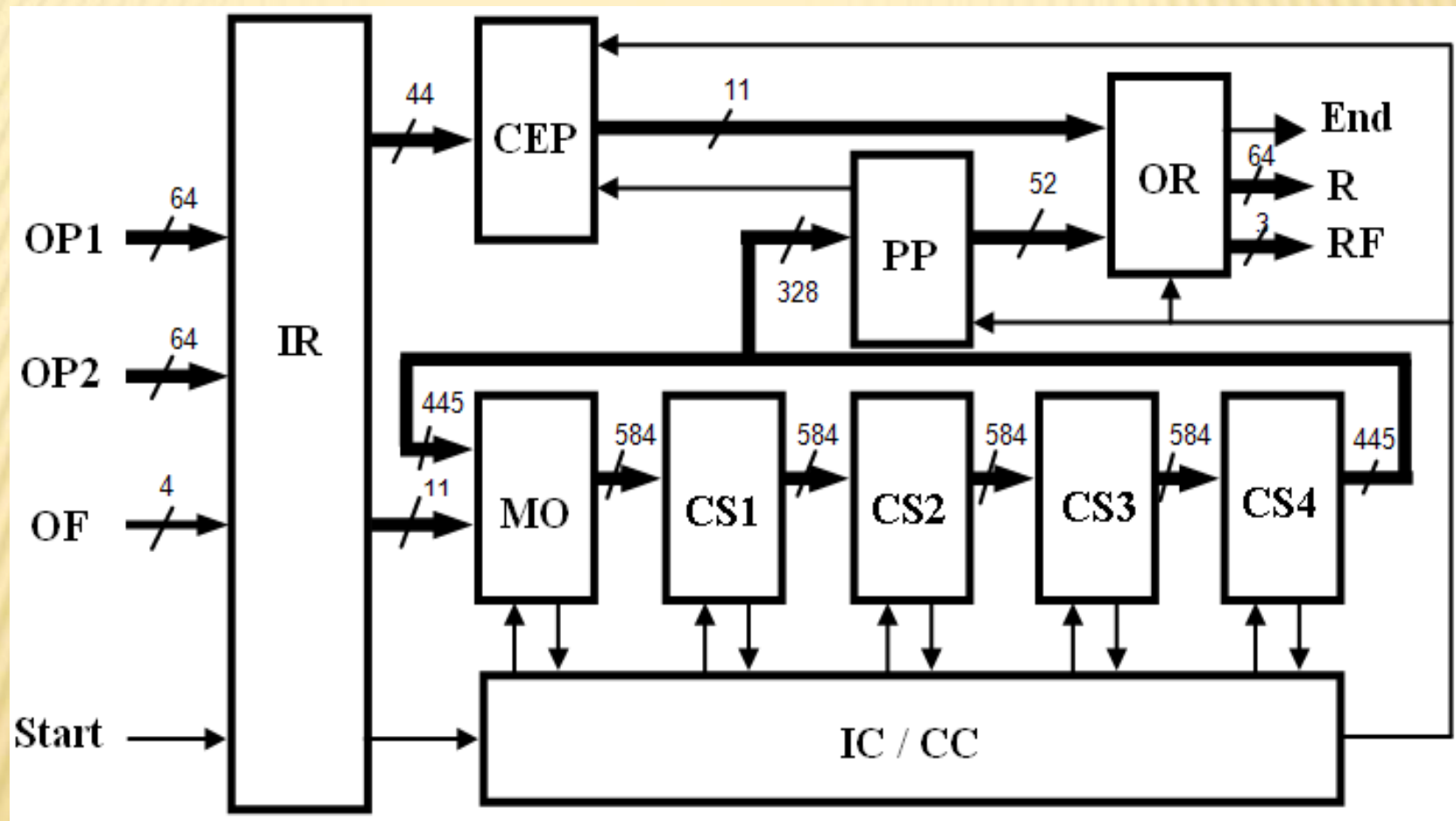
Hardware complexity on Gate Array basis

	Hardware	Synchronous, gates	Speed- independent, gates
1	Multiplier	177	444
2	Shifter	52	214
3	Counter	88	159
4	Command RAM	230	192
5	Control unit	423	380
	Total	970	1389

SI CIRCUIT EXAMPLES: MICRO CORE

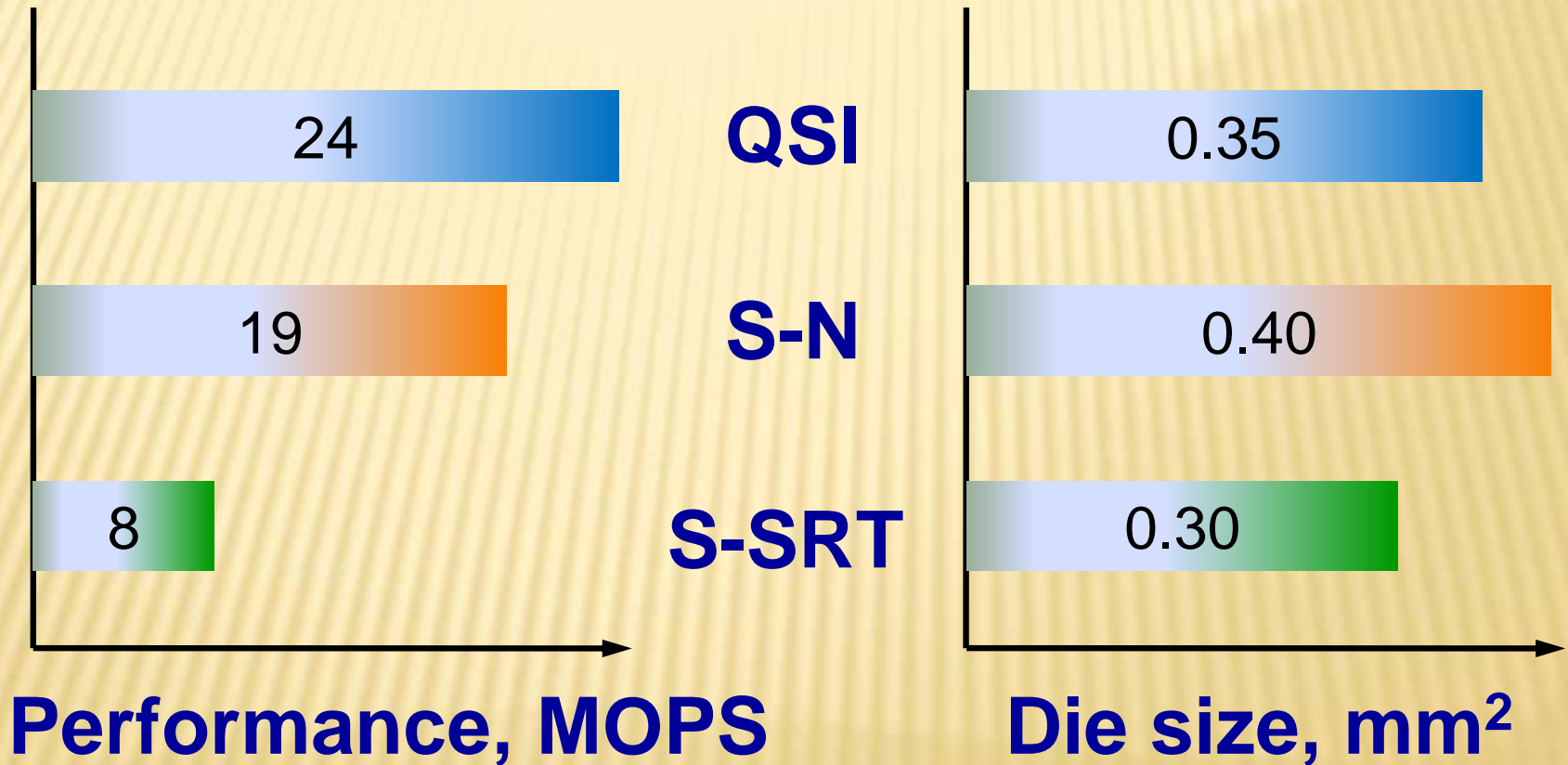


SI CIRCUIT EXAMPLES: COPROCESSOR



SI CIRCUIT EXAMPLES: COPROCESSOR

Manufactured cases comparison



SI CIRCUIT EXAMPLES: COPROCESSOR

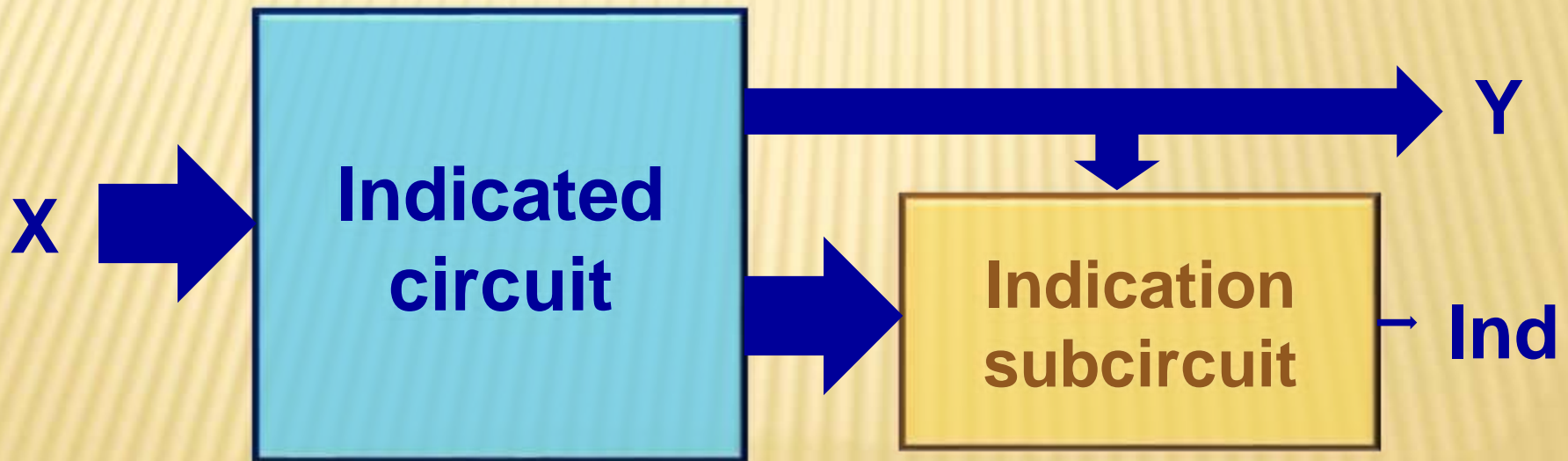
QSI and SI cases' performance, ns

	Conditions		QSI case		SI case	
	U_{DD} , V	T, °C	DIV	SQRT	DIV	SQRT
1	1.98	−63	34.7	36.9	47.3	50.2
2	1.80	25	46.7	49.1	63.5	67.0
3	1.62	125	63.9	70.3	86.9	90.1
4	0.32	125	25 688	25 301	34 940	34 410
5	0.20	125	-	-	340 800	336 920

SI CIRCUIT STRUCTURE

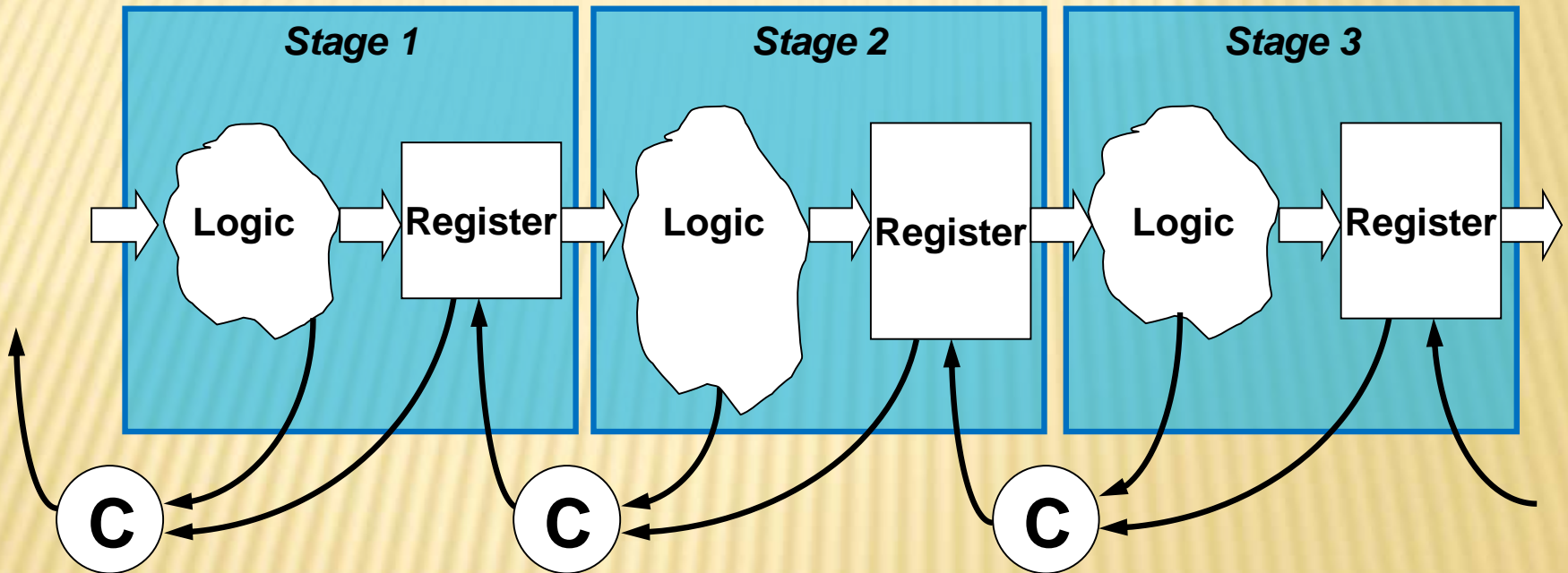
Factors limiting performance:

- ❖ Two-phase operation discipline
- ❖ An indication subcircuit acknowledging switching completion into the current phase

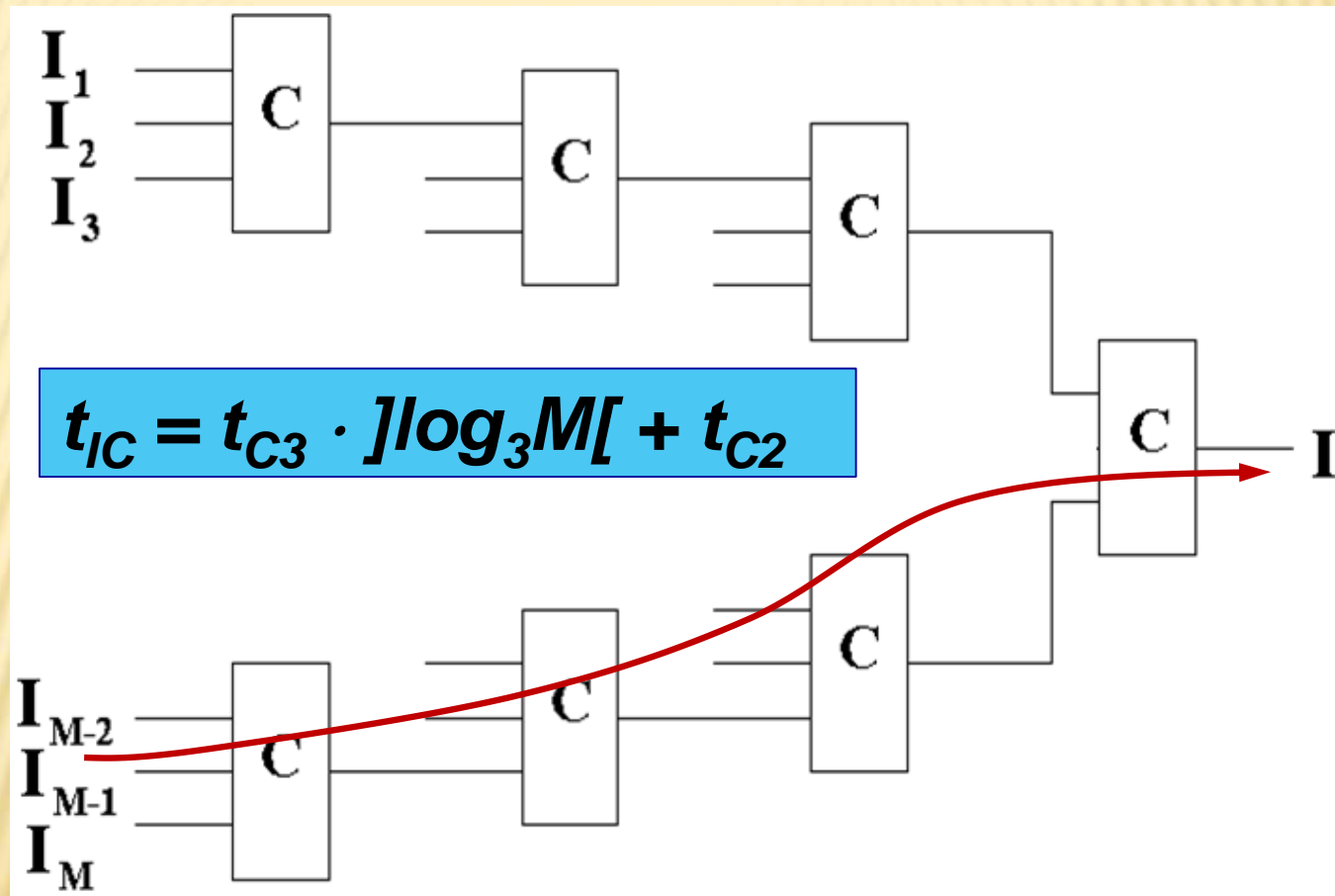


SI CIRCUIT PIPELINE

Traditional indication

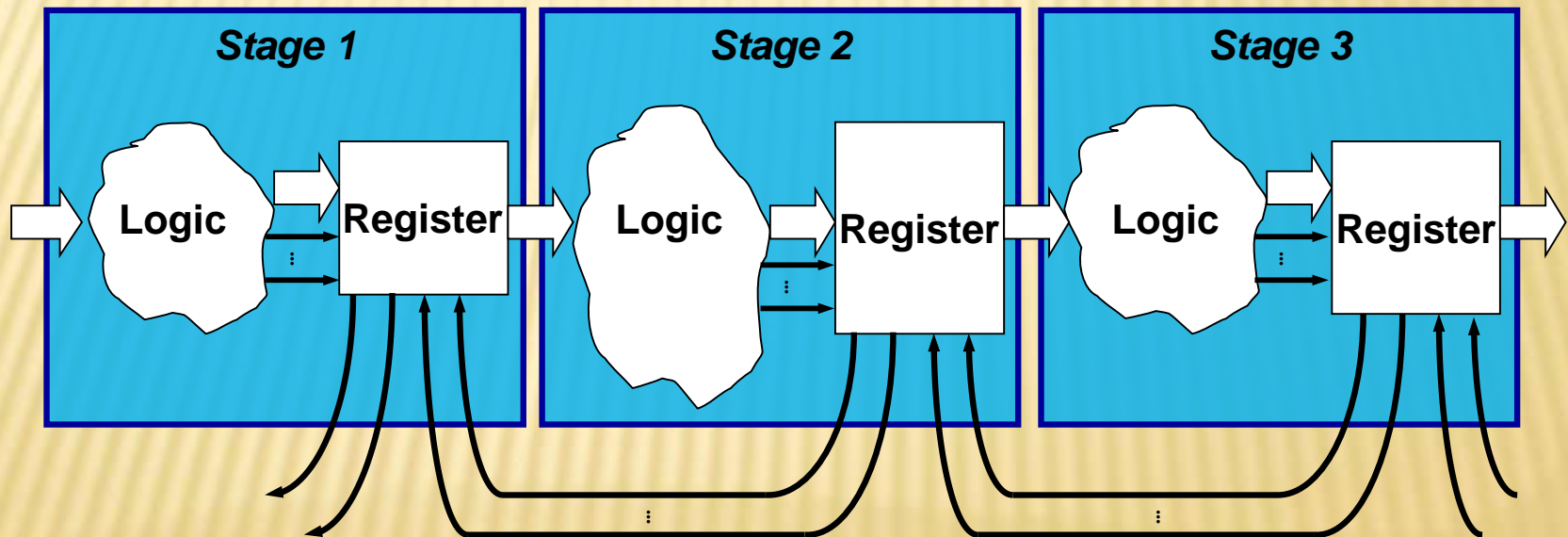


INDICATION SUBCIRCUIT STRUCTURE



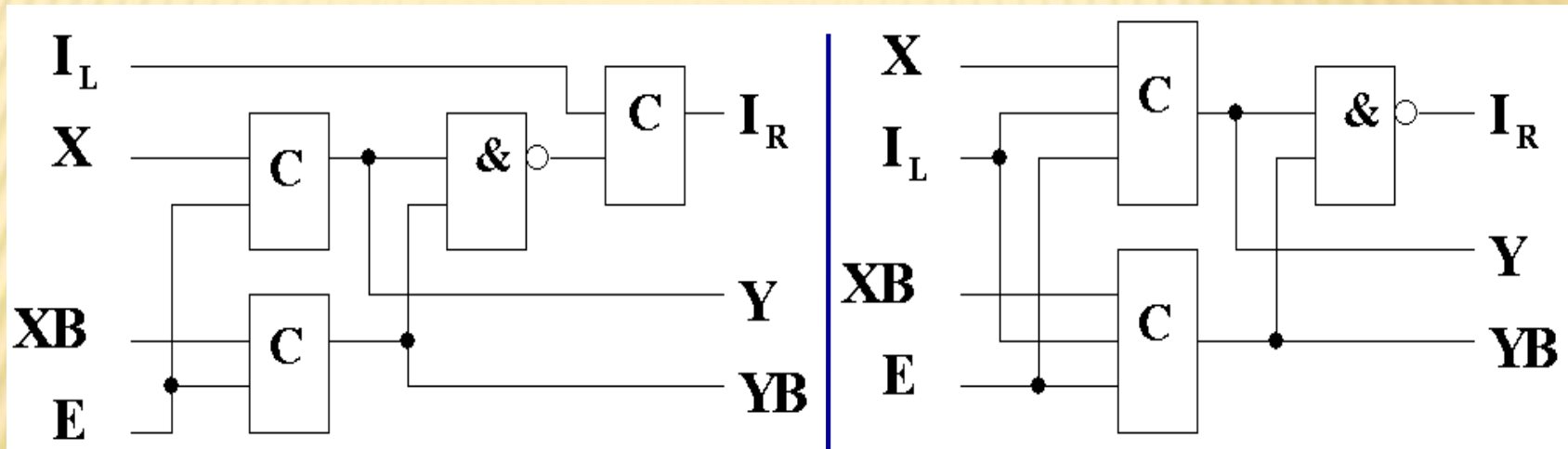
INDICATION SUBCIRCUIT OPTIMIZATION

- ❖ Bitwise indication of the Logic in the same stage Register
- ❖ Bitwise control of the previous stage Register



INDICATION SUBCIRCUIT OPTIMIZATION

- ❖ I_L is a bitwise indication output of the Logic
- ❖ I_R is a bitwise indication output of the Logic



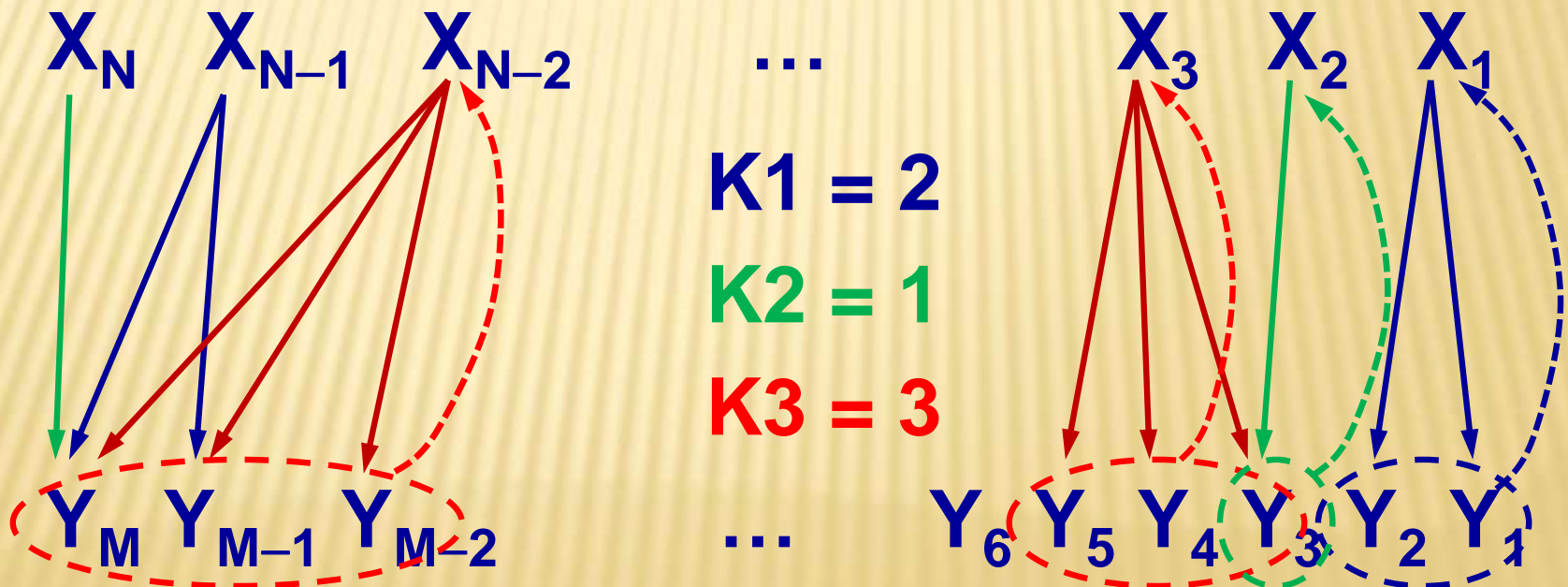
I_L delay is bigger than others input delays

I_L delay is close to others input delays

BITWISE INDICATION RULE

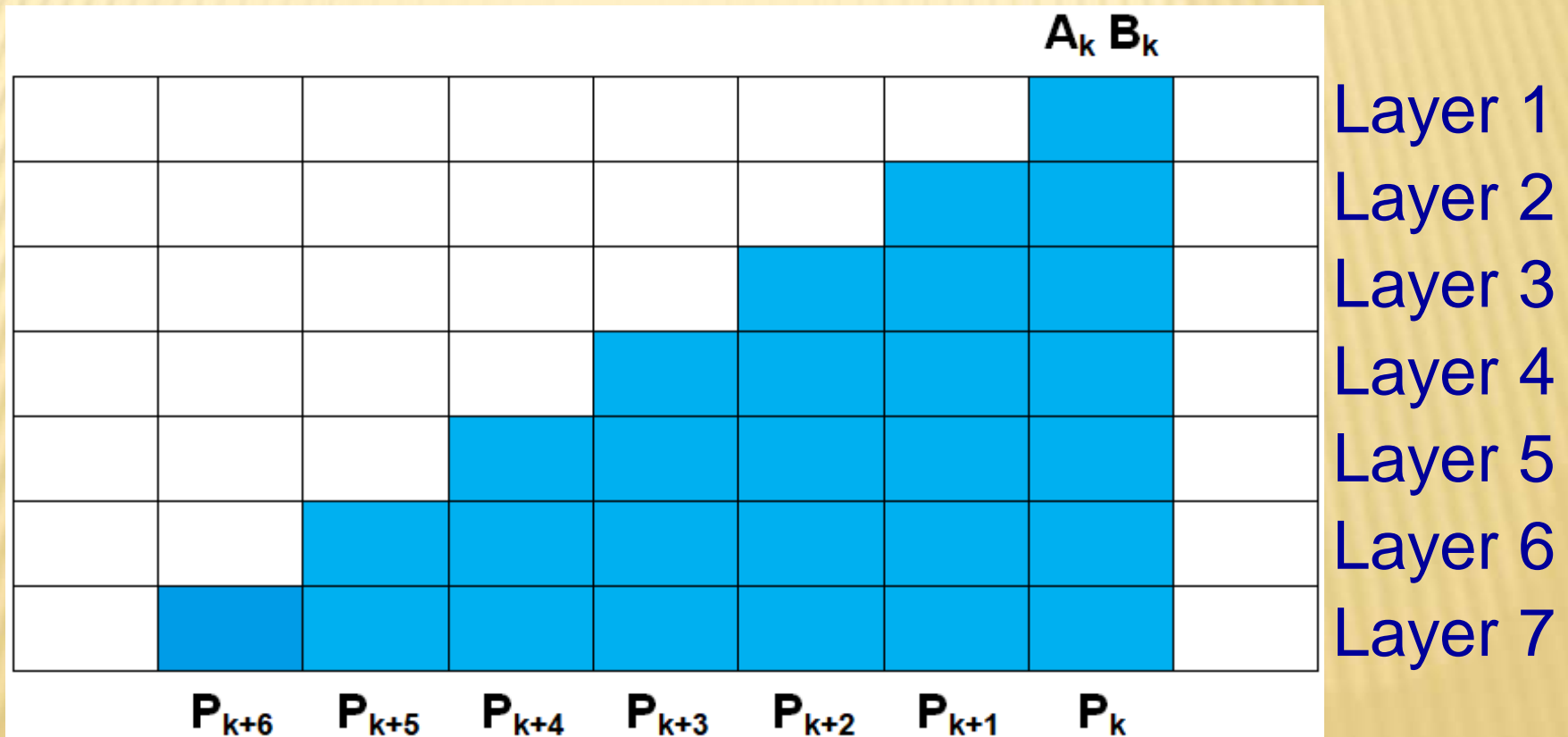
Each output controls only those inputs, which it depends on.

Connectivity coefficient “K”:



WALLACE TREE BITWISE INDICATION

For one-stage 54-bit Wallace tree, $K = 7$

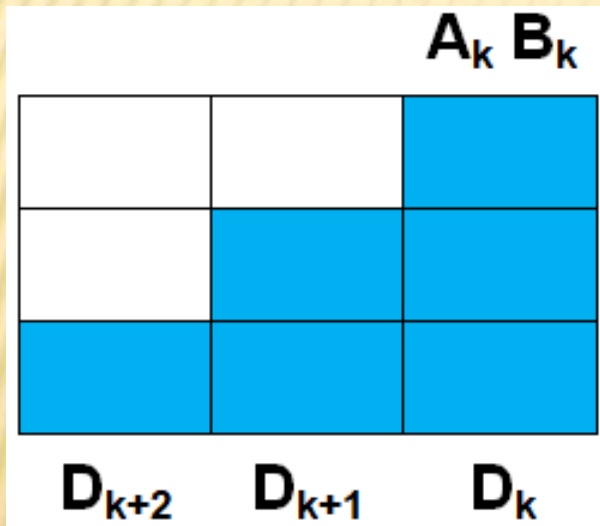


WALLACE TREE BITWISE INDICATION

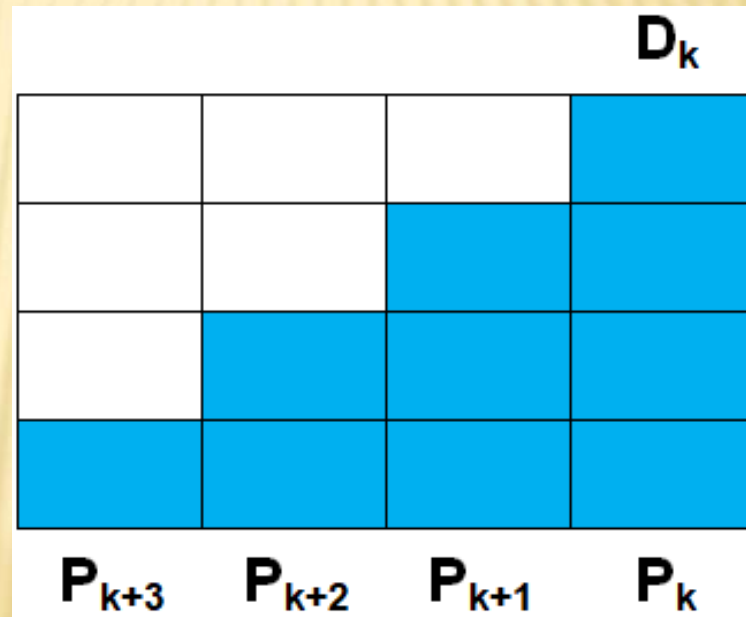
For two-stage 54-bit Wallace tree:

$$K_1 = 3; K_2 = 4$$

First WT stage



Second WT stage



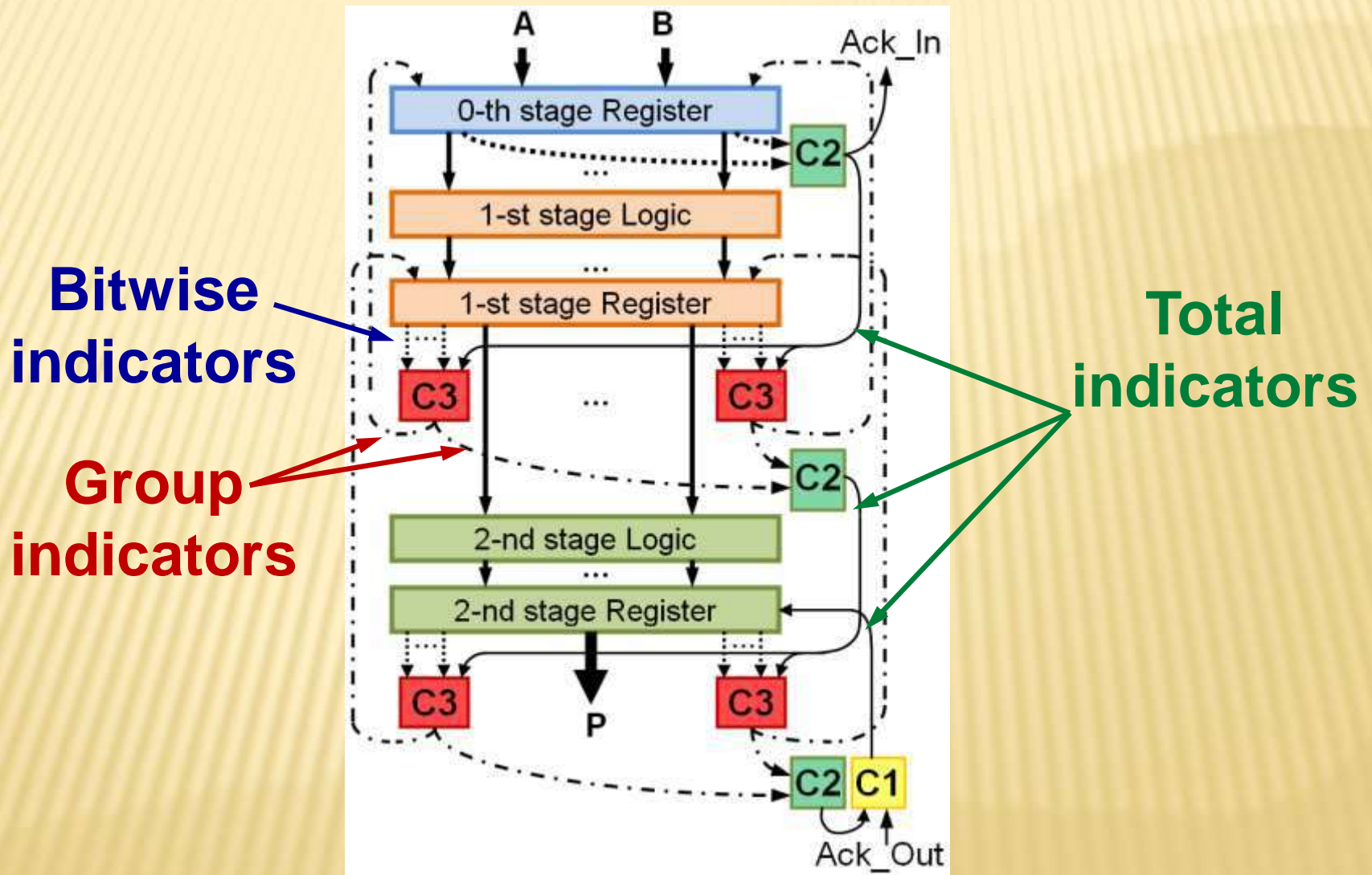
Layer 1

Layer 2

Layer 3

Layer 4

WT'S PIPELINE BITWISE INDICATION

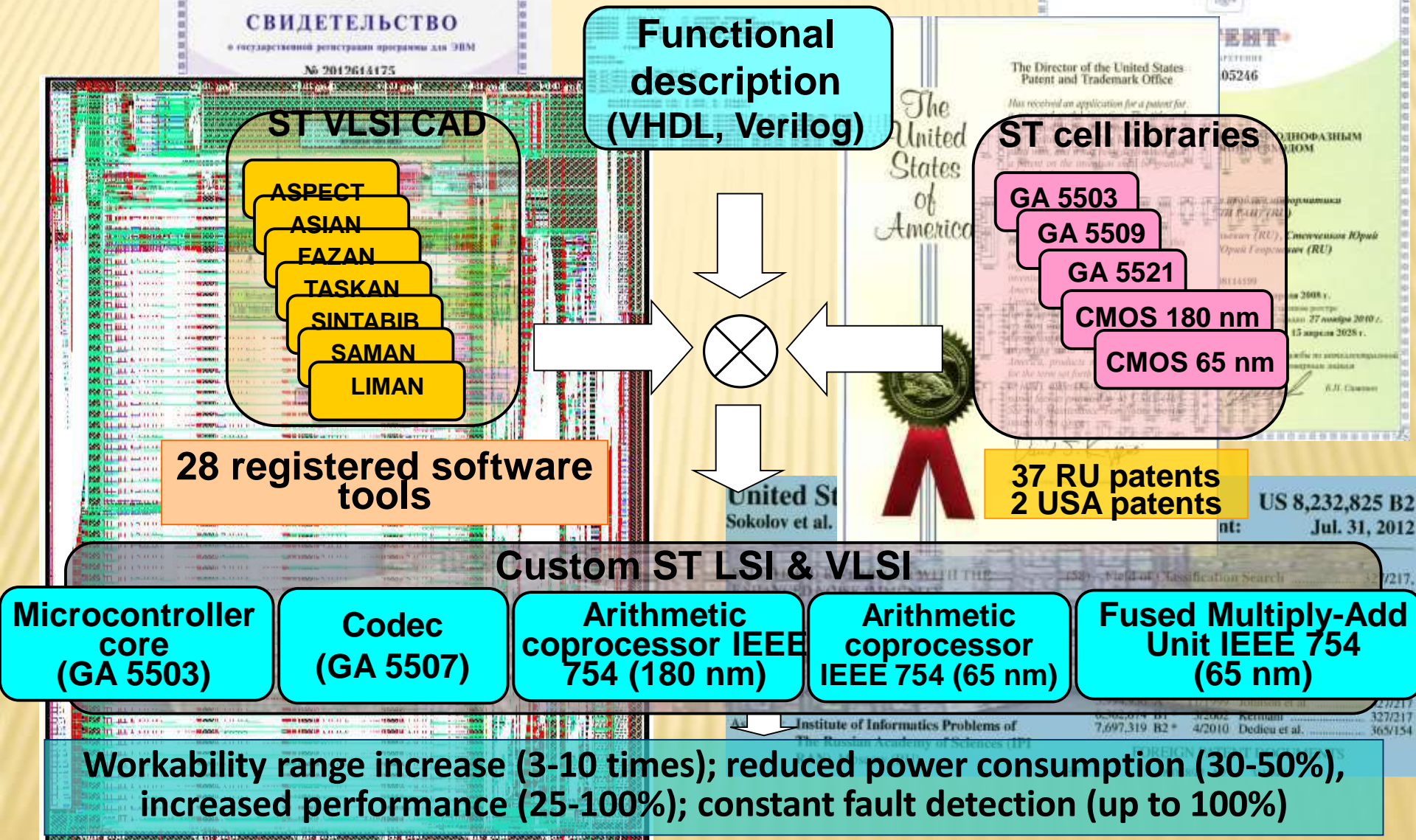


WT'S PIPELINE BITWISE INDICATION

Simulation results and hardware estimates (65-nm bulk CMOS process)

Indication case	Average cycle duration, ps	Complexity, CMOS transistors
Classical	970	220 000
Bitwise & group	710	225 500

Self-timed circuits: Design methodology, Cell libraries, CAD tools, and Product prototypes



CONCLUSIONS

- ▣ **Speed-independent (SI) circuitry is justified primarily in areas where high operational reliability is a determining factor**
- ▣ **Experimental results proved SI circuits advantages in the workability range and performance. In real conditions, typical computing speed-independent units with a low bit width of processed data have a better performance of 1.7 – 2.6 times than their synchronous analogs**
- ▣ **The use of bitwise or group indication and control in multi-bit SI circuits significantly accelerates their work at the expense of a relatively small increase in hardware complexity**

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